

# Prestress and Adhesion Site Dynamics Control Cell Sensitivity to Extracellular Stiffness

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**ABSTRACT** This study aims at improving the understanding of mechanisms responsible for cell sensitivity to extracellular environment. We explain how substrate mechanical properties can modulate the force regulation of cell sensitive elements primarily adhesion sites. We present a theoretical and experimental comparison between two radically different approaches of the force regulation of adhesion sites that depends on their either stationary or dynamic behavior. The most classical stationary model fails to predict cell sensitivity to substrate stiffness whereas the dynamic model predicts extracellular stiffness dependence. This is due to a time dependent reaction force in response to actomyosin traction force exerted on cell sensitive elements. We purposely used two cellular models, i.e., alveolar epithelial cells and alveolar macrophages exhibiting respectively stationary and dynamic adhesion sites, and compared their sensitivity to theoretical predictions. Mechanical and structural results show that alveolar epithelial cells exhibit significant prestress supported by evident stress fibers and lacks sensitivity to substrate stiffness. On the other hand, alveolar macrophages exhibit low prestress and exhibit sensitivity to substrate stiffness. Altogether, theory and experiments consistently show that adhesion site dynamics and cytoskeleton prestress control cell sensitivity to extracellular environment with an optimal sensitivity expected in the intermediate range.

## INTRODUCTION

Cell sensitivity to extracellular environment (ECE) is fundamental for many biological functions such as cell-tissue interactions, cell migration, tissue repair, and differentiation (1–4). Importantly, an ECE dependent regulation of the cell response to intra/extracellular forces raises a number of fundamental questions. The latter requires to take into account, in addition to the morphological and mechanical cell behavior (5,6), the physics of bond dissociation under force application (7,8). Surprisingly, the physical mechanisms sustaining the role of substrate relaxation have been largely occluded in the literature. A key assumption to understand these phenomena is that activation of substrate sensitive cell elements must be mechanically limited by substrate relaxation (9). Based on theoretical equations taking into account protein mechanics, substrate relaxation and traction force, it can be shown (see [Appendix](#)) that force regulation of cell sensitive elements seems to be dependent on two main factors, i.e., adhesion site dynamics and actomyosin dependent cellular prestress. Importantly, these molecular/cellular factors involve coupling between some specific intracellular or transmembrane proteins and cytoskeleton filaments. It is through these coupling mechanisms that cell sensitivity to substrate stiffness is rendered physically possible and biologically effective.

Despite the lack of theoretical understanding supporting cellular mechanosensitivity, the role of adhesion sites and

cytoskeleton prestress can be suspected from many experimental reports.

Adhesion sites are clusters of transmembrane associated proteins that link the cytoskeleton (CSK) to ECE. In response to mechanical stimuli, adhesion sites can mature through a force dependent molecular reinforcement (10). Hence, the capacity of adhesion sites to transmit forces to ECE. For instance, initial adhesion (IA) can support forces in the pN range (11), focal complex (FC) support forces in the nN range (12). Forces supported by focal adhesions (FA) may reach higher values, i.e., up to 100 nN (13). An additional key difference is that IAs and FCs are mostly dynamic adhesion sites, i.e., lifetimes vary from a few seconds to 10–20 min whereas focal adhesion lifetime is ~30–90 min (14). Noteworthy, with rupture forces in the range 40–60 pN (15) and a lifetime from 2 to 12 min (16), adhesion complexes such as podosome type adhesion (PTA) rather belong to dynamic adhesion sites. Note that podosome lifespan tend to decrease as substrate flexibility decreases (17). This study provides experimental and theoretical arguments showing that, depending on their either stationary or dynamic behavior, opposite responses can be expected in terms of force regulation by tissue rigidity.

Cellular prestress has an evident structural origin residing through tensed actinic CSK elements that are cross-linked with contractile intracellular proteins of the myosin type, resulting in intracellular tension and contraction (18–20). Acto-myosin contraction is also responsible for pulling actin filaments and generating actin retrograde motion (21). CSK prestress has been linked to the activation level of contractile

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apparatus (22). The CSK prestress dependence on cell sensitivity to ECE is consistent with previous conclusions about the key role of cytoskeletal prestress for mechanotransduction (23). However, this concept of cell sensitivity is fundamentally different from earlier concepts such as the one proposed by Chiquet et al. (23), which is based on static force equilibrium between cell and substrate. Indeed, we consider that cells sense mechanical properties of ECE in the early phase of protein-ECE or protein-CSK linkage. This time allowed for cell sensitivity to be effective is also the time required for maturation of the protein-CSK linkage. Thus, because extracellular properties trigger the development of dynamic adhesion sites, they promote force regulation of adhesion sites by ECE stiffness.

We present a coupled theoretical and experimental study of the comparison between two radically different approaches of the force regulation of adhesion sites: the classical stationary approach and what we believe is a rather new dynamic approach of cellular sensitivity to substrate stiffness. Two cellular models were purposely chosen for representing static and dynamic adhesion systems. The FA representative highly tensed cellular model was provided by alveolar epithelial cells (AECs) grown at confluence. The FC representative slightly tensed cellular model was provided by isolated alveolar macrophages (AMs) at rest. Immunostaining results show that AEC model exhibits a wide majority of stationary fully locked adhesion sites whereas isolated AMs express dynamic adhesion sites called podosomes as previously reported in the literature (16,24). Results show that the two cellular models that were tested differ consistently in terms of mechanical feature notably CSK stiffness and prestress. To focus on the sole effect of changing mechanical properties of ECE, AMs were chemically nonactivated, remaining mostly at resting state. Note that the two studied cell types are physiologically interdependent, as they interact mechanically and biologically in the same physiological environment, i.e., pulmonary alveoli (25). In this study, a mechanically active ECE was created by means of Arginine-glycine-Aspartic acid (Arg-Gly-Asp) RGD coated microbeads ( $\sim 4 \mu\text{m}$  diameter ferromagnetic or silicate beads) attached to integrin transmembrane mechanoreceptors and moved by either magnetic twisting cytometry (MTC) or optical tweezers (OT). Mechanically passive ECE was created by soft and stiff polyacrylamide gels and rigid glass/plastic substrates. It is noteworthy that experimental results confirm the validity of theoretical predictions. A predictive and synthetic diagram is proposed. It enlightens the role played by adhesion site dynamics and CSK prestress in the cell sensitivity to ECE stiffness.

## MATERIALS AND METHODS

### Type I collagen coating of glass and plastic substrate

Concentrated stocks of type I collagen (BD Biosciences; Bedford, MA) were diluted to  $20 \mu\text{g/ml}$  in 0.02 N glacial acetic acid. The diluted proteins were dispensed into 96-well culture plates, 8-well Lab-Tek (Brand products;

NUNC, Rochester, NY) chambered coverglass, and on  $22 \text{ mm} \times 22 \text{ mm}$  glass coverslips, and were incubated for 3 h at room temperature. Coated wells were routinely washed three times with sterile water, dried, and kept at  $4^\circ\text{C}$ .

### Preparation of polyacrylamide gels and coating with type I collagen

Polyacrylamide gels were prepared according to a method described previously in Pelham and Wang (26) using 10% of acrylamide and 0.3% (for soft gel) or 0.07% (for rigid gel) bis-acrylamide. Atomic force microscope (NanoWizard, JPK Instruments, Berlin, Germany) indentation was carried out to confirm that the elasticity modulus of the gels was close to expected values, i.e., 58 kPa for 0.3% bis-acrylamide and 23 kPa for 0.07% bis-acrylamide (6). Values of softer gels are close to the optimal values found by Solon et al. (27) for maximum spreading of fibroblasts. Gels were coated with  $200 \mu\text{g/ml}$  type I collagen solution (26).

### Cell isolation, culture preparation, and bead attachment

AMs were isolated from Sprague-Dawley rats by broncho-alveolar lavages and resuspended in RPMI medium supplemented with 0.1% BSA, and plated at a density of  $10^6$  cells/mL for 3 h on the various type I collagen coated substrates studied: 96-well culture plates, glass coverslips, Lab-Tek chambered coverglass (8-well), and polyacrylamide gels, as described in Féréol et al. (6).

A549 human AECs (American Type Culture Collection, Rockville, MD) were grown under the conditions described in Planus et al. (25), on the same substrates as those used for AMs. Their density was adjusted to obtain confluence at 24 h.

Before bead attachment to cells, AMs and AECs were incubated in serum free culture medium (RPMI 1640 for AMs and DMEM for AECs) supplemented with 0.1% BSA for at least 30 min at  $37^\circ\text{C}$  to block nonspecific binding. Beads were then added to the cells at a dose of 40 mg per well (96-well plates), or 100 mg per coverslip for 30 min at  $37^\circ\text{C}$  in a 5%  $\text{CO}_2$  and 95% air incubator. Unbound beads were washed away three times with serum free culture medium 1% BSA.

Carboxylated ferromagnetic beads (Spherotech, Brussels, Belgium) or carboxylated silica beads (Bangs Laboratories, Fishers, IN) of similar sizes ( $4.5 \mu\text{m}$  and  $3.5 \mu\text{m}$  in diameter respectively) were coated with the same RGD peptide (PepTite-2000; Telios Pharmaceuticals, San Diego, CA) as described in Laurent et al. (28).

### MTC

Cell elasticity modulus was assessed by an MTC device initially described by Wang et al. (29) and improved by our group to take specific geometrical factors into account (6,28,30). In the case of gel substrates, cells were grown at confluence to obtain exclusive RGD coated bead attachment to the cells.

It should be noted that, under these experimental conditions, most AMs were resting despite of the local stimuli applied by the beads. Moreover, the minority of AMs with high rigidity (e.g., migrating AMs) did not contribute to the averaged cell stiffness measured by MTC, as the MTC averaging procedure attributes a higher weight to beads experiencing large rotations (30).

To quantify cellular prestress (31), the effect of actin depolymerization on cell stiffness was studied by treating AMs and AECs with low concentrations of cytochalasin D ( $1 \mu\text{g/mL}$ ) and carrying out MTC measurements at different times (3, 6, and 11 min).

### OT

The cell elasticity modulus of AMs adherent to the gel substrate was assessed by OT using a device described previously (32). An RGD coated silica bead attached to a cell was trapped in the tweezers. The trap was then displaced at a low constant speed of  $\sim 0.1 \text{ mm} \times \text{s}^{-1}$ , i.e., under almost

quasistatic conditions and in a direction parallel to the coverslip and the cell membrane. The range of forces applied (0.1–200 pN) ensured that cellular deformations remained in the low range (<500 nm) (28). The CSK elastic modulus was determined after appropriate correction for geometric factors estimated bead by bead from the recorded microscopic images (28,30).

### F-actin and paxillin staining and 3D CSK rendering

After 3 h for adherent AMs and 24 h for AECs, F-actin and paxillin staining was carried out after fixation in paraformaldehyde (4% in phosphate buffer pH 7.4) for 10 min, then fixed cells were incubated with mouse antibody against paxillin (BD Bioscience) and rhodamine phalloidin (Sigma Chemicals, l'Île d'Abeau Chêne, France) for 45 min at 37°C. After washes, cells were incubated with Alexa 488 goat antimouse antibody for 45 min at 37°C. After final wash, cells were then covered with mounting medium and stored at 4°C overnight before observation by laser confocal microscopy (28).

Stained cell monolayers were observed using the Pascal 5 confocal microscope (Zeiss, Rueil-Malmaison, France). Image processing was carried out using AMIRA software (Version 4.1.2., Visage Imaging, Carlsbad, CA). Fields of cells were randomly selected and brought into focus using  $\times 63/1.4$  numeric aperture Plan Neofluor objective. Optical cross sections were recorded at 0.3- $\mu\text{m}$  z-axis intervals to show intracellular fluorescence. Using theoretical PSF, a stack of gray-level images (8 bits) was subjected to deconvolution before 3D visualization. Three-dimensional visualization was carried out using AMIRA software.

Three-dimensional reconstruction and rendering of CSK structure was carried out by AMIRA software using gray-level images of each confocal z-stack. Three-dimensional skeletonization of the dense polymerized CSK structure was carried out using the Skeleton pack of AMIRA software.

### Simulation methods

We compared, for quasi-static conditions, the stress fields induced at the cell-substrate interface (i.e., the 3D tensions virtually “seen” by adhesion sites on both the intracellular and the extracellular sides). Tested substrate Young modulus may differ by several orders of magnitude. We purposely used a numerical model developed previously to describe mechanical interactions between bead, cell, and substrate (6,30). In this idealized model, cell and substrate are homogeneous quasi-incompressible and hyperelastic (neo-Hookean) continuum characterized by a classical strain energy function already used in tissues and living cells (33) and given by  $W = a_1(I_1 - 3)$  where  $a_1$  is the cell constant (in Pa), whereas  $I_1$  is the first invariant of the right Cauchy-Green strain tensor  $C$  [ $I_1 = \text{Trace}(C)$ ]. In this model, the traction applied by the cell to the different substrates is induced by a bead partially immersed in the cell and through which a constant torque is applied. The cell Young modulus is fixed at a constant physiologically relevant value of 100 Pa. We assumed no-slip boundary conditions at the bead-cell interface and at the cell-substrate interface. The substrate was attached to a nondeformable base. The bead surface was modeled as a rigid shell whose stiffness is far larger than the cell stiffness. Simulations were carried out under static conditions. Computations of the stress fields corresponding to torques  $750 \text{ pN} \times \mu\text{m}$  were carried out using a resolution method described in a previous study (30).

## RESULTS

### Experimental evidence of the distinct features of AECs and AMs

#### *Actin CSK structure and adhesion protein localization*

After fixation and double staining of F-actin and paxillin (see [Materials and Methods](#)), AECs and AMs adhering on the same type I collagen coated glass substrates were compared for their F-actin organization and the localization of typical

adhesion protein near the basal plane. We used a cumulative view made of z-stack images within a 1- $\mu\text{m}$  thick layer from the basal cell plane (Fig. 1, *a–d*). Actin and paxillin are representative of the physical link existing between F-actin CSK and ECE. These cellular elements are present at the cell-substrate interface in the two cellular models used (Fig. 1, *a* and *b*). Such a result was expected as focal adhesion and podosome both contain actin and paxillin (14,24,34). Three-dimensional skeletonization of F-actin structure in AECs (Fig. 1 *c*) and in AMs (Fig. 1 *d*) shows marked differences in the dense CSK architecture (in *white*) between AECs and AMs. In Fig. 1, *c–f*, the horizontal (Fig. 1, *c* and *d*) and vertical (Fig. 1, *e* and *f*) distribution of paxillin is shown by a spatial reconstruction that evidences its aggregation. Marked differences exist in the horizontal distribution of paxillin between the two cellular models used. In AECs, the dense F-actin network near the basal plane covers the entire cell due to multiple interconnections between short and long dense actin stress fibers (Fig. 1 *c*). The later are generally terminated by focal adhesion plaques (visible through reconstructed aggregates of paxillin, in *green*) notably located on cell periphery in AECs. In AMs (Fig. 1 *d*), the dense F-actin network does not extend throughout the entire cell, forming either punctuated structured or only local network, except at the origin of the circumferential lamellipodium. The presence of a highly structured actin network at the cell edge of AECs and further inside the cell is consistent with the assumption of cellular stability for this type of tissue cell grown to form a monolayer. Punctuate structures of dense F-actin essentially found near basal face of AM body are not commonly observed although this is consistent with the finding that AMs adhere to their substrate through localized and dense actin core developing vertically. These actin structures are usually surrounded by a diffuse membrane domain of integrins and associated proteins such as paxillin forming adhesion complex of the podosome type (14,24,35).

#### *Mechanical response to increasing externally applied stress*

The responses of: 1), AECs (forming a confluent monolayer); and 2), AMs (essentially resting) to increasing magnetic torques applied through RGD coated beads (see [Materials and Methods](#)), were compared over  $\sim 1$  min of stress application, in adherent cells on type I collagen coated plastic substrate. The short-term cellular response expressed in terms of CSK elastic modulus (Fig. 2) and cellular deformation (Fig. 3) were evaluated at four increasing levels of magnetic torques ranging from 400 to 1300  $\text{pN} \times \mu\text{m}$ . The results show that resting AMs are clearly softer than AECs, and that AMs and AECs exhibit a markedly different behavior in the short-term response to increasing levels of externally applied stress. AECs exhibit a highly significant stress dependent increase in cell stiffness (almost linear stress hardening as shown in Fig. 2) corresponding to nonlinear torque-rotation relationship (shown in Fig. 3). In contrast,



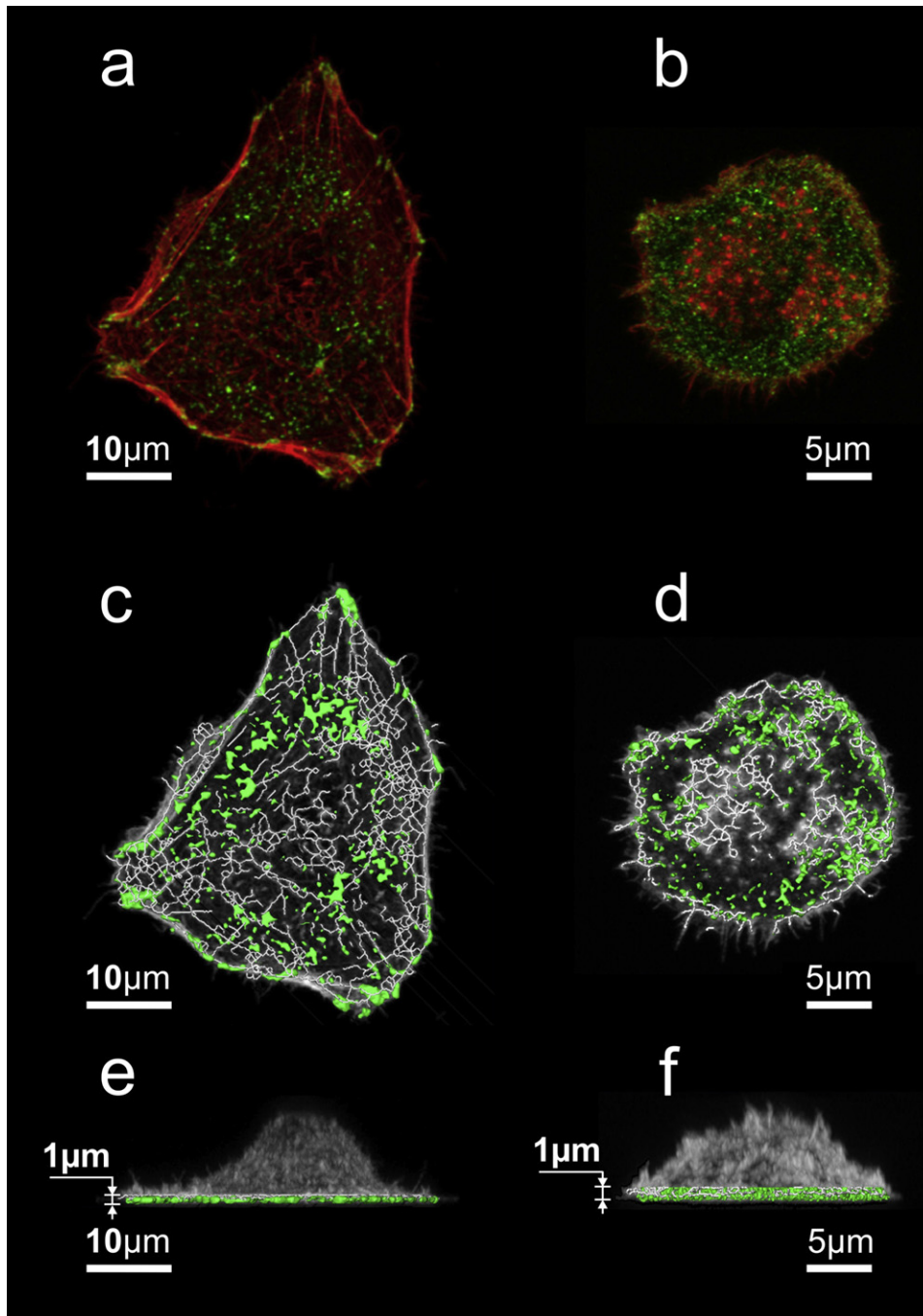


FIGURE 1 (*a* and *b*) Cumulative views of F-actin and paxillin in fixed AECs (*a*) and AMs (*b*) adhering on the same type I collagen coated glass substrates. These images were made of z-stack of confocal images within a 1- $\mu$ m thick layer from the basal cell plane. (*c* and *d*) Top view of 3D skeletonization and 3D reconstructions of the aggregated paxillin obtained in the same AECs (*c*) and AMs (*d*) from the images shown in (*a* and *b*). (*e* and *f*) Side view of 3D skeletonization and 3D reconstructions of the aggregated paxillin obtained in the same AECs (*e*) and AMs (*f*) from the images shown in (*a* and *b*).

AMs exhibit a stress independent cell stiffness throughout the entire range of torque tested (shown in Fig. 2), i.e., quasi-linear stress-strain relationship (shown in Fig. 3). Considering the intermediate to large range of cellular deformation measured, (i.e., 20°–50° of bead rotation corresponding to 900–2100 nm of circumferential bead displacement shown in Fig. 3), it is reasonable to consider that the response of cells structured with stress fibers such as AECs reflect higher geometric nonlinearity than cells lacking stress fibers such as AMs.

#### *Mechanical response to decrease in internal tension*

AECs and AMs exhibited a different response after treatment with low concentrations of cytochalasin D (see [Material and Methods](#) and Fig. 4). Although the elastic modulus of AMs remained unchanged for 12 min after blockade of actin polymerization (i.e., from time zero in Fig. 4), AECs exhibit a rapid and significant decrease in elastic modulus after only 6 min of cytochalasin D treatment. The fall in cell stiffness reaches 35% at 11 min. The rapid drop in cell stiffness

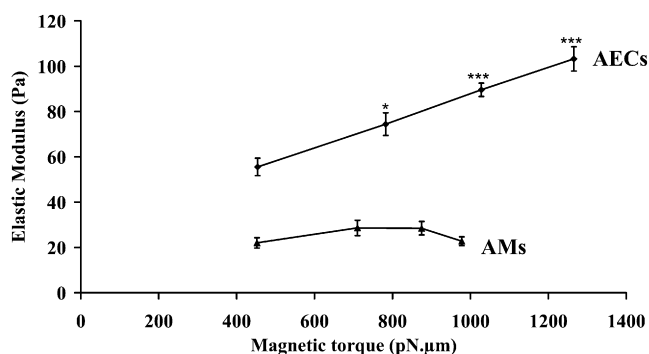


FIGURE 2 The CSK elastic modulus (in Pa) or stiffness of AECs and AMs is measured by RGD coated ferromagnetic beads ( $\sim 4.5 \mu\text{m}$  in diameter) using the MTC technique for four different magnetic torques in the range  $400 \text{ pN} \times \mu\text{m}$ – $1300 \text{ pN} \times \mu\text{m}$ . There is a highly significant increase in CSK elastic modulus with magnetic torque for AECs (stress hardening cell response) and an almost constant CSK elastic modulus with stress increase (stress independent cell response). Values are expressed as a mean  $\pm$  SE. Each value is the mean of three independent measurements. The statistical test used is the ANOVA test. (\* $p < 0.05$ ; \*\*\* $p < 0.001$ ).

observed is given to reflect the specific actinic contribution to cell stiffness that can be related to the level of cellular prestress (31,36). At the low concentration and short duration of treatment used, cytochalasin D mainly affects the deep and dense actin CSK (e.g., stress fibers in AECs) and only minimally cell shape at least in living AECs (37). This cellular response to a decrease in internal stress caused by cytochalasin D shows the significant level of prestress in AECs compared to the nonmeasurable level of prestress in AMs. Incidentally, if tension in the actomyosin network is considered to be determinant for stress fiber formation (38), it seems logical that low stressed cells such as AMs lack actin bundles, and subsequently not exhibit a structural

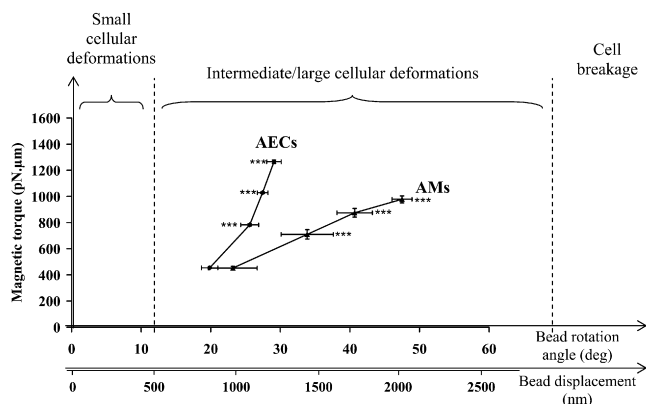


FIGURE 3 The magnetic torque (in  $\text{pN} \times \mu\text{m}$ ) is plotted versus the bead rotation angle (in degrees) or its equivalent in terms of bead displacement (in nm) calculated at the surface of a  $4.5\text{-}\mu\text{m}$  diameter bead, for AECs and AMs. MTC measurements correspond to an intermediate to large range of cellular deformations (from  $500 \text{ nm}$  to  $2000 \text{ nm}$ ). Note that the OT method used here (see Materials and Methods) operate over the range of small cellular deformation (28). We postulate that cell breakage might occur in the highest range of cell deformations. Values are expressed as mean  $\pm$  SE. Each value is the mean of three independent measurements. The statistical test used is the ANOVA test. (\*\* $p < 0.01$ ).

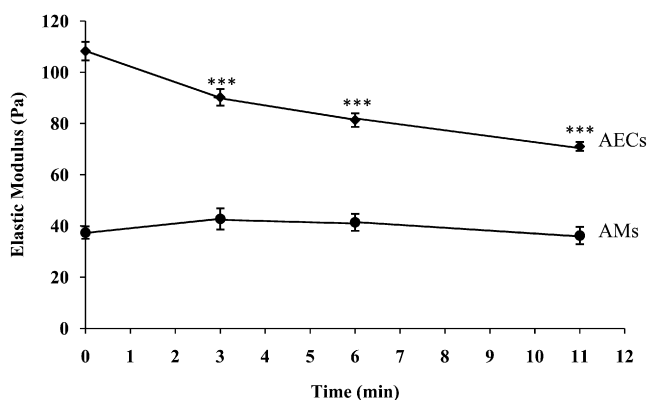


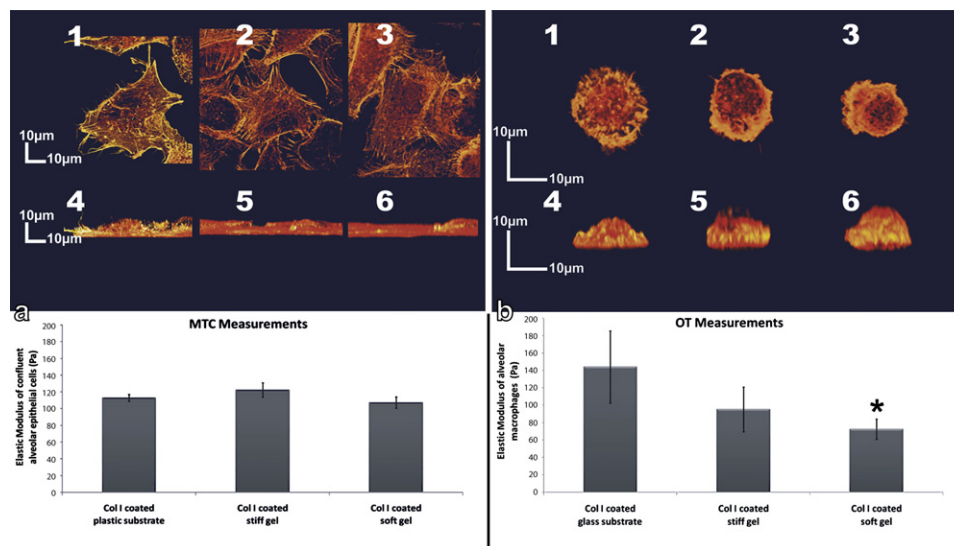
FIGURE 4 The CSK elastic modulus (in Pa) of AECs and AMs in the 11 min after an actin-depolymerizing treatment with cytochalasin D. Measurements were carried out with MTC. Slight differences in absolute values of AMs elastic modulus found with Fig. 1 remain in the statistical range of error. As shown previously (31), the decay in CSK elastic modulus during cytochalasin D treatment can be related to prestress. Values are expressed as mean  $\pm$  SE. Each value is the mean of three independent measurements. The statistical test used is the ANOVA test. (\*\* $p < 0.01$ ).

nonlinear behavior with increasing stress. It should be also noted that the bead twisting method used here allows an estimate of cell prestress in noncontractile cells. This method does not necessarily reflect the very local intracellular tensions distant from the bead, (e.g., those tensions generated by punctual adhesion structures in the basal plane).

### Experimental evidence of the distinct substrate stiffness sensitivity of AECs and AMs

The long-term responses of the two cellular models to type I collagen coated substrates with three different levels of stiffness are compared in Fig. 5. Cells were allowed to adhere to these substrates for 24 h (for AECs) and 3 h (for AMs). The three substrates tested were: 1), rigid substrate made of plastic (for MTC measurements) or glass (for OT measurements) (i.e., Young modulus,  $E_s \geq 3 \text{ MPa}$ ); 2), stiff polyacrylamide gel substrate (i.e.,  $E_s \approx 58 \text{ kPa}$ ); and 3), soft polyacrylamide gel substrate (i.e.,  $E_s \approx 23 \text{ kPa}$ ).

Three-dimensional visualizations of F-actin structures (Fig. 5 a, top (AECs) and b, top (AMs)) confirm the differences at the cellular level between F-actin structures of AECs and AMs, as already shown in Fig. 1. Another important message provided by these actin structure visualizations shown in Fig. 5 is that very different substrate stiffness did not affect the stress fiber organization or shape of AECs, e.g., the maximal height of the AEC monolayer remained close to  $8\text{--}10 \mu\text{m}$  for all substrates tested. The lack of sensitivity of AECs to substrate properties is confirmed by MTC measurements of AEC elastic modulus showing that AEC stiffness is not affected by the marked changes in substrate rigidity (Fig. 5 a, bottom graph). In contrast, AM shapes seem to differ according to the substrate. Fig. 5 b, 3–1, illustrate the slight but significant increase in basal area of AMs whereas Fig. 5 b, 6–4, illustrate the decrease in cell height observed with increasing substrate



**FIGURE 5** The effect of substrate stiffness on F-actin structures and CSK elastic modulus (in Pa) is shown in (a) for AECs and (b) for AMs. Three type I collagen coated substrates of different stiffness values were tested, i.e., successively from left to right in (a and b): plastic/glass substrate ( $E_s$  [Young modulus]  $\geq 3$  MPa; stiff gel [ $E_s = 58$  kPa]; soft gel [ $E_s = 23$  kPa]). Images in (a, 1–6) provide for AECs and (b, 1–6) for AMs, 3D visualizations of F-actin structure from cumulated images of confocal planes viewed from top (a, 1–3 and b, 1–3) and from the side (a, 4–6 and b, 4–6). Graphs on bottom of (a and b) represent respectively the elastic modulus (in Pa) of confluent AECs (measured through RGD coated ferromagnetic beads by MTC) and resting AMs (measured through RGD coated silicate beads by

OT) plotted for the three different substrates tested. Note that different scales are used in (a and b). Values are expressed as mean  $\pm$  SE. Each value is the mean of three independent measurements. The statistical test used is the ANOVA test. No significant differences were observed in AECs.

rigidity from soft gel to rigid glass. This AM sensitivity to substrate stiffness is confirmed by the significant increase in AM elastic modulus observed when substrate stiffness changed from soft gel to rigid glass (Fig. 5 b, bottom graph).

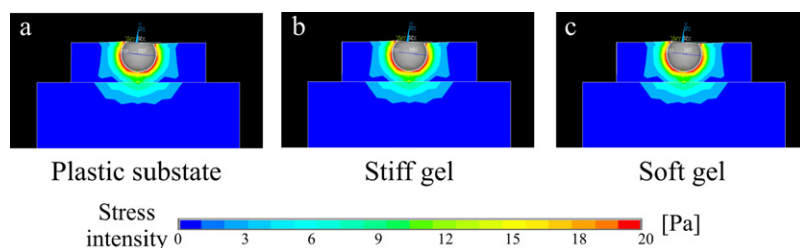
Another interesting feature of actin structures (Fig. 5, a and b) concerns the differences in cell internal tension between the two cellular models studied. Internal tension in AECs can be estimated from the centripetal curvature that characterizes most of the long actin stress fibers that are tensed between anchorage points to the substrate, i.e., typically the stationary focal adhesion (FA) plaques located at the end of stress fibers. Such tensed stress fibers do not exist in AMs, consistently with the lack of prestress measured by MTC.

### Theoretical prediction of the distinct substrate stiffness sensitivity of AECs and AMs

#### Quasi-static simulations of the stress field at the cell-substrate interface

We used a numeric model of the bead-cell-substrate mechanical interactions to validate in 3D the assumption that reac-

tion forces exerted by the substrate on a stationary adhesion site could not depend on substrate rigidity. In such a case, a constant torque is applied to the bead and generates a 3D stress field extending down to the cell-substrate interface. The higher the torque and/or the stiffer the substrate, the deeper the stress propagation inside the substrate. To verify that substrate stiffness does not affect the 3D stress field at given torque, we numerically simulated the effect of a constant torque (i.e.,  $750 \text{ pN} \times \mu\text{m}$  in simulations) applied to a cell of predetermined and constant elastic properties (i.e., Young modulus of cell fixed at  $100 \text{ Pa}$ ), adhering on three different substrates tested (i.e., Young modulus of  $3 \times 10^6 \text{ Pa}$  for plastic,  $58 \times 10^3 \text{ Pa}$  for stiff gel, and  $23 \times 10^3 \text{ Pa}$  for soft gels). The simulated stress fields shown in Fig. 6 are strictly the same despite profound changes in substrate elasticity properties. Thus, intracellular stress fields, generated by a twisted bead, could not be affected by substrate stiffness. These results confirm that adhesion sites located at cell-substrate interface could only see the same stress field despite deep change in substrate stiffness. Thus, the reaction forces exerted by the substrate on a stationary



**FIGURE 6** Three-dimensional stress fields calculated by numerical simulation for the three substrates tested in the experimental study: (a) rigid plastic substrate (3000 kPa), (b) stiff gel (58 kPa), and (c) soft gel (23 kPa). The planar cross sectional views of the 3D stress field are obtained for a constant magnetic torque (i.e.,  $750 \text{ nN} \times \mu\text{m}$ ) applied by a partially immersed bead ( $4.5 \mu\text{m}$  in diameter,  $130^\circ$  of half angle of bead immersion) in an isolated cell of constant Young modulus property ( $100 \text{ Pa}$ ) continuously attached to the three substrates tested. This numerical simulation assumes linearly elastic materials, continuity conditions

at the cell-substrate interface and static equilibrium between bead, cell, and substrate. Note that, despite very different stiffness properties of the substrate, the stress field “seen” at the cell-substrate interface is the same for the three very different substrates studied. This simulation is a new demonstration that the stress distribution of an elastic medium subject to a localized external force exerted on its surface does not depend on the stiffness of the medium.

adhesion site and its force sensitive proteins could not be dependent on substrate rigidity. It strongly suggests that activation of stationary adhesion site containing force sensitive proteins cannot be regulated by substrate rigidity.

#### Comparison between stationary and dynamic cell-substrate adhesion

The predicted behavior of dynamic adhesion sites is presented in Fig. 7 in terms of the relationship between normalized dissociation force and substrate stiffness (see Appendix). In the dynamic adhesion model, once the filament bundles “locks” the adhesion site, retrograde motion of the filament vanishes and the full traction force  $T$  is applied to the adhesion site. According to the model, there is no possibility to return to the logarithmic lower branch. AECs monolayer correspond to the upper branch of the graph ( $S$  range: 0–1) where adhesion sites are fully locked and behave independently on substrate stiffness. In contrast, AMs correspond to the intermediate branch of the graph in Fig. 7, i.e., the zone of the graph corresponding to substrate dependent adhesion site reinforcement. Noteworthy, in this zone, an increase in substrate stiffness can promote reinforcement simply because the rate of increase of the reaction force  $F_{\text{ex}}(t) = k V_R t$  in Eq. A4 increases. In such a case, the time to reach the level where the site locks is shorter. Note

that excessively soft substrates correspond to lowest rates of increase in reaction force and adhesion sites lose the possibility to reach the critical force level  $F_c$  ( $S = 0$ ) for locking. Note also that for immature adhesion sites such as  $S \approx -1$ , the level of dissociation energy is so low that the adhesion sites have no chance to reinforce, i.e., a stiffened substrate is not sufficient. In these conditions, the adhesion site would remain always immature, and therefore fully slipping.

## DISCUSSION

This study proposes what we believe is a new understanding of cellular sensitivity to substrate stiffness. We purposely used complementary theoretical and experimental approaches of this well recognized but not fully understood phenomena. Based on this coupled approach, we compare two radically different theories of the force regulation mechanism, namely a classical theory describing stationary adhesion sites and a newly proposed theory describing dynamic adhesion sites. It is noteworthy that the most classical stationary model fails to predict cell sensitivity to substrate stiffness whereas the newly proposed dynamic model provides a rationale to this mostly obscure phenomenon. These two models are discussed thoroughly and confronted with experimental results. The two cellular models used for this confrontation are 1), AECs; and 2), AMs that exhibit respectively stationary and dynamic adhesion sites. An important finding of this study is the consistency between experimental results and theoretical predictions, namely the cellular model with stationary adhesion site and high internal tension does not exhibit sensitivity to ECE stiffness, whereas the cellular model with dynamic adhesion sites and low or moderate internal tension exhibits sensitivity to ECE stiffness. Because testing adhesion sites isolated from their intra/extracellular environments has no meaning, we tested the sensitivity of cellular models chosen for their capability to represent these two different states of adhesion and intracellular prestress. An important message brought by the dynamic model is that cellular sensitivity to substrate stiffness is possible because, in response to actomyosin traction forces exerted on initial cell sensitive element, a reaction force grows with time and, remarkably, remains proportional to substrate elasticity and intracellular tension.

In terms of cell sensitivity to substrate stiffness, experiments and theory show the role of two important parameters, e.g., adhesion site dynamics and cytoskeleton prestress. These two parameters enlighten the close connection existing between molecular and cellular mechanisms for the control of cell sensitivity to substrate stiffness. Indeed, the role of adhesion dynamics results from molecular considerations issued from the stochastic processes of bond rupture usually characterized by single molecule force spectroscopy experiments (8,39–41). The role of intracellular tension results from cellular considerations after assessment of the actinic contribution to cytoskeleton mechanics (42–44). The recent model of force regulation by nascent adhesion sites proposed

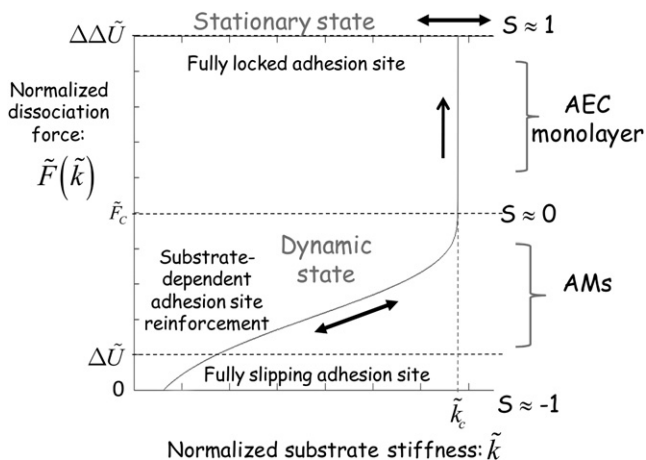


FIGURE 7 The normalized most likely dissociation force  $\tilde{F}(\tilde{k})$  for a given adhesion site is plotted versus the normalized substrate stiffness  $\tilde{k}$  (given by Eq. A7). The values of the state parameter  $S$  increase from  $-1$  to  $+1$  as the energy level required for adhesion site dissociation increases.  $S \approx -1$  corresponds to the lowest level of dissociation energy ( $\Delta\tilde{U}$ ) and thus to a fully slipping adhesion site. AM adhesion sites would correspond to an intermediate range of  $S$  values ( $-1; 0$ ) corresponding to the transition between logarithmic dependence and the increasing contribution of elastic energy associated to the displacement (i.e.,  $0.5 k(\rho - V_R t)^2$ ). In this zone, the adhesion site is in a dynamic state and substrate dependent changes are reversible. Beyond a critical value of substrate rigidity  $\tilde{k}_c$  which is difficult to determine more precisely in this study (see Appendix), the adhesion site is reinforced and fully transmits the actomyosin traction force to the substrate. Adhesion sites of AECs pertain to this zone ( $S$  values in the range  $(0; +1)$  in which adhesion sites are stationary and irreversibly reinforced. The highest level of dissociation energy  $\Delta\Delta\tilde{U}$  is observed for  $S \approx +1$ .



by Bruinsma (9) provides further support to earlier protein mechanic models, which all predict a dissociation force that is logarithmically dependent on the loading rate (8). Note that protein mechanic models usually consider a reversible chemomechanical activation of adhesion proteins, i.e., between a passive and an active state that is related to conformational change of integrins (7,45). Importantly, in the dynamic adhesion site model, because the equilibration time for site activation is due to mechanical relaxation and not to chemical equilibration, mechanical relaxation is a factor permitting—thus controlling—cell sensitivity to substrate stiffness. The dynamic adhesion site model also assumes that the actin bundle—to which the adhesion site is connected via a potential energy—is exposed to a constant effort resulting from constant activation of intracellular motors responsible for internal tension or contractility. The important feature of the dynamic adhesion site model (governed by Eq. A4) is that—in response to an imposed constant actomyosin loading force—a time dependent reaction force exists and raises with time, allowing the adhesion site to initiate its maturation, i.e., developing toward either site reinforcement or bond rupture. The rate at which the reaction force increases depends on the substrate elasticity and actomyosin motors activation level through respectively the  $k$  and  $V_R$  term dependence of the slope of the time dependent reaction force. These predictions are consistent with current biological experiments showing that the issue of adhesion site development, i.e., toward either site maturation or bond rupture, depends on extracellular and intracellular conditions. It can be said that a faster rate of increase in the reaction force  $F_{ex}(t)$  results in a faster linkage of adhesion site or otherwise, in a higher number of binding-dissociation-rebinding cycles that may in turns favor adhesion site reinforcement. Comparing this dynamic adhesion site model to a stationary adhesion site model, it seems that the behaviors of these two models are completely different in terms of substrate dependence of force regulation. In response to intracellular traction (internal tension or contraction), the nanoscale motion of the dynamic adhesion site is governed in the early phase of its development by the elasticity of the substrate and intracellular traction force. Note that the higher intracellular traction force, the higher intracellular prestress, the higher the reaction force. It seems also reasonable to consider that substrate stiffness dependent cellular sensitivity could be favored by rapid and thus nondistant transmission of intracellular forces, a typical configuration encountered in podosome-like structures of AMs (35) and not in focal adhesion structures of AECs.

We are aware that the results (Fig. 5) only provide a “time-integrated” view (i.e., over several hours). This time is much longer than the mechanical relaxation time associated to adhesion site maturation,  $\tau (= \gamma_R/k)$ , i.e.,  $\sim 0.1$  s per actin filament that gives relaxation time in the range  $10\text{--}10^2$  s for an actin bundle, letting plenty of time for adhesion site development. On the other hand, the mechanical relaxation time is much longer than the time required for chemical equilibration that

is consistent with the above mentioned assumption that the rate limiting step for activation is mechanical and not chemical. Moreover, due to the lack of knowledge about the dynamics of proteins unfolding and the uncertainty on molecular organization (e.g., cooperative bonds acting in parallel or noncooperative bonds acting in series), it is difficult to accurately estimate the values of critical substrate stiffness  $\tilde{k}_c$  and reference value of substrate stiffness  $k_0$  proper or each substrate (see Fig. 7 and Appendix). Hence, the difficulty to quantitatively estimate the dissociation forces associated to the different conditions tested.

## Predictive diagram

The experimental and theoretical results can be presented schematically in a synthetic diagram (Fig. 8). This diagram

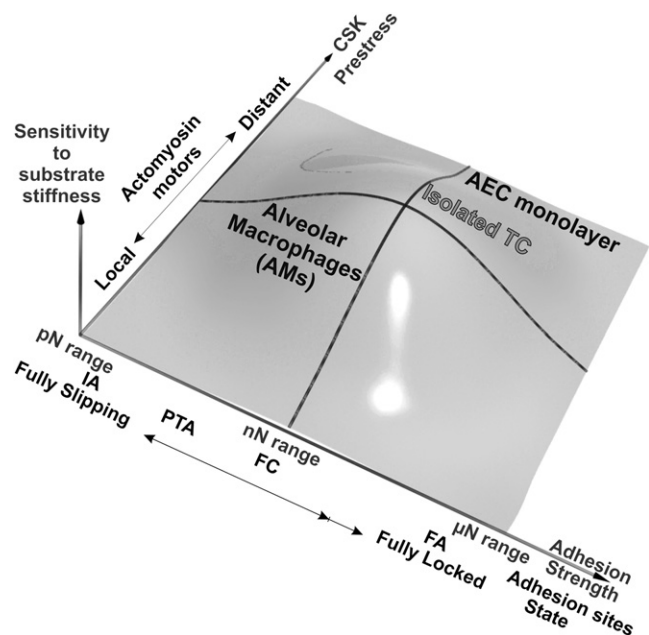


FIGURE 8 Synthetic diagram predicting the variation in the cellular sensitivity to substrate stiffness as a function of two determinant parameters plotted on the two horizontal axis: 1), adhesion force reflecting the state of adhesion sites; and 2), CSK prestress reflecting actomyosin contractility. The adhesion strength increases as adhesion site is reinforced: pN range for IA, nN range for premature FC, and  $\mu$ N range for mature FA. PTA characterizing macrophage adhesion is right in between IA and FC in terms of adhesion site strength and dynamic state. Adhesion site contractility is susceptible to change from local scale, e.g., in podosomes (PTA), to global scale, e.g., in stress fiber network, the intermediate situation for prestress corresponding to actomyosin contractility in lamellipodia, also responsible for actin retrograde velocity. This diagram is consistent with both the theory (described in Appendix) and the experiments. Confluent tissue cells such as AECs in monolayer are usually highly stressed cells with a fairly stationary focal adhesion system. They exhibit almost no sensitivity to substrate stiffness as predicted by the stationary adhesion site theory. When isolated, tissue cells can express dynamic adhesion sites and recover their sensitivity to substrate stiffness. Resting AMs with low or intermediate internal stress and essentially dynamic adhesion sites exhibit a net sensitivity to substrate stiffness. The diagram also predicts that unstressed cells with essentially fully slipping adhesion sites cultured on very soft substrates would lack sensitivity to substrate stiffness.



predicts cell sensitivity to substrate stiffness as a function of the two main parameters imposed by both theoretical considerations and experimental results: 1), state or strength of adhesion sites; and 2), CSK prestress or alternatively contractility generated by actomyosin motors. The biphasic shape of this diagram represents the recent knowledge acquired from both experimental results and the theoretical models presented in [Appendix](#). It shows that cell sensitivity to substrate stiffness is optimal for an intermediate range of the mechanobiological parameters. It requires dynamic but locked adhesion sites and intermediate CSK prestress or moderate actomyosin activation. It means that the sensitivity of cellular elements that arises from coupling between specific mechanosensitive proteins (e.g., adhesion proteins) can only be optimal for a certain range of functioning. This is consistent with recent findings concerning the biphasic behavior of cellular (bell shaped) models predicting that substrate stiffness influences many cellular processes such as spreading or traction forces. These models may be thermodynamics (46), kinetic (47) or even purely mechanical (48). Note that substrate stiffness has been thought to be a more important determinant for cell shape than the density of adhesive ligands to which the cell binds (46).

The first horizontal axis (strength of adhesion sites) represents the maximum force supported by a given adhesive link, (i.e., represented by  $\bar{F}(\bar{k})$  in [Appendix](#)). This strength depends on the adhesion site molecular structure and the content of the adhesion site. The simplest link in terms of molecular adhesion structure corresponds to initial adhesion (IA). IA can support forces in the pN range (49) and slips at higher forces—a phenomenon called “slipping clutch”—but preventing adhesion linkage at higher forces. For totally slipping adhesion sites (i.e.,  $S \approx -1$ ; see [Appendix](#)), the force regulation by substrate stiffness may not be effective as the site dissociates before binding. If IA matures to FC, over an interval of about one minute, the link with CSK would be reinforced due to a larger number of constituent components such as vinculin or paxillin. Therefore, the adhesion structure would be able to support forces in the nN range (12). The clutch has engaged that is well described by the degenerate free energy condition  $S \sim 0$  (see [Appendix](#)). In this range of intermediate strength, i.e., for FC adhesion site structure, the dynamic adhesion site theory described in the [Appendix](#) predicts force regulation by substrate stiffness, hence the prediction of maximum sensitivity given by the diagram. The FA structure can support forces approaching 100 nN, i.e., close to the  $\mu$ N range (50). FA take much longer to achieve this molecular reinforcement, FA require much more time than FC to become fully established ( $\sim 1$  h) (51). Although fully mature adhesion sites (FA) remain important centers for cell signaling by reversibly adjusting their size to the applied force (52), they remain insensitive to substrate stiffness for the theoretical reasons explained in the first part of the [Appendix](#).

The second horizontal axis of the diagram represents prestress, which corresponds to the level of endogenous contractile tension in the CSK generated by actin-myosin II interactions. It is well represented by the traction force applied to actin bundle ( $T$  in [Appendix](#)). Based on these experimental results, we consider that the prestress level differs according to local or distant generation of actomyosin motors. Podosomes can only generate a local prestress—not measurable by bead twisting from the apical side of AMs. By contrast stress fibers can propagate the tensile prestress over long distances throughout the cell structure (53), contributing to the elevated prestress measured in AECs. Note that prestress in highly contractile cells has been shown to remain proportional to cellular stiffness (42).

The level of endogenous contractile prestress generated by actomyosin contraction is known to play a key role in the cellular adaptation to stress (18,54). The use of myosin II inhibitors such as blebbistatin has provided additional evidence that actomyosin activity plays a key role in the cellular adaptation to an externally applied mechanical stress (55). Incidentally, this active adaptation may be seen as complementary to the structural, essentially passive, cellular adaptation. Nonlinear and passive behavior of highly prestressed and largely deformed cellular structures is well described by the tensegrity model (22,29,56).

It is now recognized that maturation and strengthening of adhesions sites are dependent on internal CSK forces and/or extracellular stimuli (10,12,57). Moreover, the role of actomyosin contractility on maturation of adhesion sites has been demonstrated by using actomyosin inhibitors (57,58). Similarly, it has been shown recently that mechanical reinforcement—one of the key response of the cell to locally applied stress—is synonymous of actin recruitment and higher actomyosin contraction (59). If we consider that substrate stiffness also regulates actomyosin contraction and thus endogenous tension, one may expect higher reaction force and, for sufficient substrate stiffness, enhanced reinforcement and faster maturation of the adhesion site. Moreover, the assembly of stress fibers and focal adhesion is known to be regulated by the small GTPase Rho (60). Besser and Schwarz (61) have made a mechanochemical model of the stress fiber reinforcement and increase in contractility induced by the Rho pathway. The model describes the biochemical process of Rho diffusion throughout the cytoplasm, the viscoelastic properties of a stress fiber tensed between two focal adhesion sites and the variable contractile properties of the stress fiber under the variable Rho concentration. Although providing a coupled view of biochemistry and mechanics in the control of stress fiber contraction, this model does not account for the initial reinforcement of adhesion sites and thus could not describe the cellular sensitivity to substrate stiffness. Moreover, it is known that in cells that do not express stress fibers and focal adhesion system such as macrophages, Rho does not directly regulate actin cytoskeleton and focal

complex adhesion system (62) and is not required for migration (63).

AECs forming a monolayer occupy a low sensitivity zone located in the basal part of the diagram (Fig. 8) where prestress and strength linkage to ECE are both significant. This lack of substrate sensitivity of AECs forming a monolayer is thought to be representative of other tissue cells, which would therefore be situated in the same region of the diagram. For instance, Yeung et al. (5) found similar results in a confluent monolayer of endothelial cells—evidenced by maintenance of a constant cell area—despite very different substrate stiffness. We can consider from these results that subconfluent and confluent cells do not totally diverge in terms of structure, shape, or mechanics, which means that the subconfluent or confluent character does not affect these sensitivity results. First, the subconfluent cells structures shown in Fig. 5 *a*, *top*, do not appear significantly modified by substrate stiffness. Second, we carried out measurements of CSK stiffness in subconfluent and confluent A549 cells earlier (31) and found no difference in CSK stiffness, stiffening response, and prestress. These past results and the results presented here are totally consistent with the earlier results obtained in fibroblasts by Yeung et al. (5), who found that as soon as tissue cells are able to make cell-cell contacts, they form stress fibers even when there are grown on soft substrates. These authors also noticed that endothelial cells behave in a similar fashion; precisely they need to be sparse enough and noteworthy lack cell-cell junctions to recover a stiffness dependent morphology and structure. To explain their results, Yeung et al. (5) assumed that cell-cell adherent junctions formed between endothelial cells involve cadherin activation that could override the ligand activated integrin signal. We propose a physically founded explanation for the lack of AECs sensitivity. Based on paxillin staining in AEC model that shows that cell-matrix adhesion maintains the anchorage of the monolayer to the substrate (Fig. 1), it can be said that the significant level of prestress found in AEC monolayer could not be uniquely balanced by cell-cell adhesion. According to these results, it can be said that stationary adhesion sites of AEC monolayer keep maintaining the stability of AECs monolayer in a substrate independent manner. In a case where AECs would adopt a migrating phenotype and then become isolated, they would recover their sensitivity to ECE stiffness (see the more central position of tissue cells in Fig. 8) as experimentally shown by Yeung et al. (5). This is because nonstationary adhesion sites of tissue cells are regenerated as required for cell migration. Migrating isolated fibroblasts have been shown to express this type of sensitivity to substrate stiffness via migration guided by substrate rigidity, a phenomenon called durotaxis (2).

Resting AMs occupy a central zone in the diagram (Fig. 8) consistent with our experimental results and theoretical predictions. With rupture forces in the range pN–nN (15), lifetimes not exceeding 12 min (16), dynamic adhesion complexes or podosomes of macrophages are close to FC

and thus in the middle region of adhesion site axis. The reasons why macrophage adhesion sites remain in the dynamic state and do not mature toward stationary adhesion sites is beyond the scope of this study. The phagocytosis function of macrophages has been shown to most likely require the development of high contractile forces (64). Note that phagocytosing AMs do not lose their sensitivity to extracellular stiffness properties because objects with identical chemical properties but different stiffness are preferentially engulfed when they are stiff (65). The results on AMs adherent to coated gels as well as previous results on AMs adherent to epithelial cells (6) show that AMs adapt their shape to ECE stiffness while missing stress fibers. This is surprising as stress fibers have been thought to be determinant for mechanotransduction in tissue cells (23,53,66). These results on AMs raise a number of questions concerning the nature of mechanotransduction pathways in cells like AMs. Indeed, these cells do not have a prestress mediated force transmission system such as that described by Wang et al. (53). We proposed recently that microtubules that terminate at podosomes (16,24) could play a role in mechanotransduction of AMs (6). Podosomes, as dynamic adhesion structures also myosin II dependent adherent actin microdomains, are able to provide an ECE dependent cell regulation that might be facilitated by the local generation of contractile forces (17,35,67). These short-lived punctuate actin rich adhesion structures also allow AMs to be sensitive to ECE stiffness, most likely generating a local prestress limited to the adhesion site region as suggested by the results of this study. This local contractile activity is consistent with the moderate cellular prestress characteristics of our resting AMs. RGD coated beads essentially located on the apical surface of the cells cannot measure this local prestress, essentially limited to the adhesion site (PTA) vicinity. Altogether, the results obtained in the two cellular models support the concept that intracellular structure and adhesion site function in coordination at different scales to regulate the cellular response to ECE.

Note that in interactions of AMs with other cell types, organic and inorganic materials are essential for many lung functions such as adhesion to alveolar epithelium, particle recognition, and selective destruction, which all imply specific and essentially dynamic adhesion sites. In addition, cell-cell interactions of AECs with other alveolar cells and matrix that would rather involve stationary adhesion sites are essential for alveolar stability. An alteration of either AM or AEC interactions with ECE is responsible for many pathological reactions leading to either fibrogenic, granulomatous, destructive, or inflammatory processes.

## APPENDIX: SIMPLIFIED THEORY OF FORCE REGULATION BY ADHESION SITES

We consider the simplest model made of a discrete adhesion site of constant size “ $a$ ” ( $\sim A^{1/2}$ ,  $A$ : area of adhesion site) located at the surface (parallel to  $x$ -y plane) of a linearly elastic semi-infinite medium characterized by a substrate

Young modulus ( $E_s$ ) (9). The adhesion site is exposed to active and passive unidirectional forces acting at the interface between the substrate and the cell. The active force, generated by an actomyosin contraction, is transmitted to the site by an actin bundle and is related to internal tension. Traction force is directed along the  $x$ -axis and potentially results in adhesion site displacement along the same  $x$ -axis direction. The passive force results from the viscoelastic reaction of the substrate to this active force. Alternatively, internal tensions that promote adhesion site assembly could be replaced by application of external forces (14). The aim of Appendix is to enlighten the role of physical parameters governing the substrate stiffness sensitivity in stationary and dynamic adhesion sites, and their relationship with overall cell scale and ECE properties.

## Stationary adhesion site

In its simplest form, the adhesion site can be considered to be in an almost static equilibrium between a traction force ( $T$ ) transmitted via a bundle of actin filaments and a recoil force generated within the viscoelastic substrate, in response to the traction force. Note that the traction force can be generated either intracellularly by actomyosin motors or extracellularly by a probe provided it is physically connected to the cytoskeleton, e.g., an RGD coated bead as in this study. Regardless of its origin, i.e., intracellular or extracellular, the traction force generates a local stress distribution whose area integral is equal to the traction force ( $T$ ). According to linear elasticity theory, the three components of the resulting elastic displacement of the substrate are all inversely proportional to the substrate Young modulus ( $E_s$ ), i.e., the stiffer the substrate, the smaller the displacement at a given applied stress. Displacement ( $u_0$ ) of the adhesion site center of size “ $a$ ” is given by  $u_0 \approx T/(E_s \times a)$  ( $= (\sigma_0/E_s) \times a$ ), with  $\sigma_0 (=T/A)$  the spatial average of the applied force  $T$ , showing that the substrate acts as a harmonic spring of constant  $k (\approx E_s \times a)$  whereas  $u_0$  always remains proportional to  $T$ . This type of property has been used to deduce the traction force from the displacement field (57). Noteworthy, away from the adhesion site, e.g., at a distance “ $r$ ” from the adhesion site, substrate stress remains proportional to external stress  $\sigma_0$ , times the square of the  $a/r$  ratio, but does not depend on substrate rigidity, i.e.,  $\sigma_{xx}(x=r, y=0, z=0) \approx -\sigma_0[(\sigma_p+2)/2\pi](a/r)^2$ , with  $\sigma_p$ : Poisson ratio. The reaction forces exerted by the substrate on a stationary adhesion site are therefore independent of substrate rigidity. Hence, the linear elasticity theory suggests that force regulation of stationary adhesion sites can only occur via a reversible change in adhesion site area. Interestingly, it has been shown that focal adhesion areas are approximately proportional to the applied forces (52).

## Dynamic adhesion site

If not stationary, the adhesion site is dynamic and its nanoscale time dependent displacement has to be considered. Noteworthy, the force regulation model proposed by Bruinsma (9) considers the relative displacement,  $\rho(t)$ , between the actin filament bundle and a linked adhesion site (Fig. 9). If  $Z(t)$  is the absolute position on  $x$ -axis at instant  $t$  of the filament bundle and  $X(t)$  the absolute position of adhesion site in such way that  $X(t=0) = Z(t=0) = 0$ , then the relative adhesion site displacement can be written:  $\rho(t) = Z(t) - X(t)$ . It is also assumed that dynamic—not fully mature—adhesion sites do maintain their size “ $a$ ” constant while changing their state as maturation occurs. The filament bundle is exposed to a traction force  $T$  directed along  $x$ -axis. The adhesion site is exposed to a force  $F$  parallel to  $T$  that derives from a potential energy of linkage between the adhesion site and the CSK.  $F$  can only be a small fraction of the actomyosin traction force  $T$  to which the actin bundle is exposed. The state of the adhesion site reversibly varies between an inactivated (or passive) state ( $S = -1$ ) and an activated state ( $S = 1$ ), thus taking into account an integrin activation induced by phosphatase activity triggered by a force induced conformational change of adhesion site integrins. This is a specificity of the model proposed by Bruinsma (9) compared to previous molecular bond studies (8,39–41).

Calling  $\Delta G$  the Gibbs free energy difference between these two states in the absence of applied force, the thermodynamic work carried out by the applied force during such conformational change is  $Fd^*$ , where  $d^*$  is the

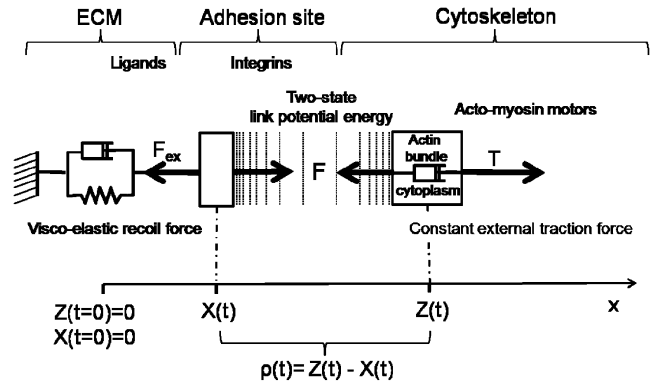


FIGURE 9 Schema of the dynamic adhesion site model. The dynamic adhesion site model takes into account the chemico-physical link: cytoskeleton, adhesion site and extracellular matrix (ECM), and the associated forces and mechanical properties. The adhesion site and the actin bundle can move along the axis direction  $x$  under the action of constant traction  $T$  exerted on actin bundle and the viscoelastic recoil exerted by the substrate on the adhesion site. The relative distance between the adhesion site and the actin bundle is called  $\rho(t)$ . The link between adhesion site and actin filament bundle is described by a “two state” potential energy of mean force whose state varies between passive ( $S = -1$ ) and active ( $S = +1$ ) (Fig. 7). This mechanochemical reaction is assumed to involve conformational change of the adhesion site integrins (see text for explanations).

characteristic length scale of the molecular displacement, i.e., in the nm range (8,39,41). Under chemical equilibrium conditions, the likelihood value of the site variable  $S$  is given by:

$$\langle S \rangle_F = \tanh \frac{1}{k_B T} (-\Delta G + Fd^*). \quad (A1)$$

In these experiments, the state variable  $S$  characterizing AM adhesion sites is assumed to be within the range  $[-1-0]$  whereas for AEC adhesion sites the range would be  $[0-1]$ .

The adhesion site is exposed—on the cellular side—to a force derived from the potential energy  $U(\rho, S)$  describing the mechanochemical linkage between actin filaments and the adhesion site. The adhesion site is exposed—on the substrate side—to a recoil force resulting from the viscoelastic reaction of the substrate. The latter is made of the viscous drag  $\gamma_B \frac{dX}{dt}$  proportional to friction coefficient  $\gamma_B (\approx \eta a)$  added to the recoil force  $-kX$  proportional to the spring constant  $k (\approx E_s a)$  where  $a$  is the unchanged size of the—not fully mature—adhesion site.  $f(t)$  is the thermal random noise exerted on the site provided by fluctuation-dissipation theorem. Then, the equation of motion of the site is given by:

$$\gamma_B \frac{dX}{dt} + kX = \frac{dU(\rho, S)}{d\rho} + f(t). \quad (A2)$$

The equation of motion of actin filament bundle is obtained by setting the equilibrium between the sum of forces exerted on the bundle—on cellular side—constant traction force ( $T$ ), the link force, the thermal fluctuation random force  $f^*(t)$  and the viscous retarding force,  $\gamma_R \frac{dZ}{dt}$ , resulting from the friction between actin filaments and the cytoplasm (friction coefficient:  $\gamma_R$ ).

$$\gamma_R \frac{dZ}{dt} = \frac{dU(\rho, S)}{d\rho} + T + f^*(t). \quad (A3)$$

$T (= \gamma_R \times V_R)$  is responsible for the retrograde motion of the actin bundle at the constant velocity  $V_R$ .

Combining equations of motion for adhesion site (Eq. A2) and actin filament bundle (Eq. A3) and assuming times much shorter than the mechanical

relaxation time, i.e.,  $t \ll \tau = (\gamma_B + \gamma_R)/k$  ( $= \gamma_R/k$  because  $\gamma_B \ll \gamma_R$ , a condition indeed verified by the values given below for polyacrylamide gels), the relative motion of the adhesion site of coordinate  $\rho(t)$  can be described by a Langevin equation:

$$\gamma_B \frac{d\rho}{dt} + k(\rho - V_R t) \cong -\frac{dU(\rho, S)}{d\rho} + \gamma_B V_R + f(t). \quad (\text{A4})$$

Equation A4 describes the nanoscale motion a particle of coordinate  $\rho(t)$  moving in a double-well link potential  $U(\rho, S)$ , subjected to the constant traction force  $\gamma_B V_R$  and a time dependent reaction force  $F_{ex}(t) (= k V_R t)$  despite the assumption of constant traction force.

For 1- $\mu\text{m}$  wide site and the three substrates tested in this study (plastic, “stiff” gel, “soft” gel), the spring constant is:  $k = 3000$  pN/nm, 58 pN/nm, and 23 pN/nm, respectively. Corresponding values of  $\gamma_B$  for the polyacrylamide gels tested remain within the range:  $3 \cdot 10^{-1} - 3 \cdot 10^{-4}$  pN  $\times$  s/nm (C. Verdier, Centre National de la Recherche Scientifique, personal communication, 2008).  $\gamma_R$  is of the order of 0.1 pN  $\times$  s/nm per filament, i.e., 10–100 pN  $\times$  s/nm for  $10^2$ – $10^3$  filaments per actin bundle. Thus  $\gamma_B \ll \gamma_R$  is a condition indeed verified by the values given above for polyacrylamide gels.  $V_R$  is in the  $\mu\text{m}/\text{mn}$  and characterizes actin dynamics in the lamellipodia. Values of  $k V_R$  were 48,000 pN/s, 928 pN/s, and 368 pN/s, respectively, for the three substrates tested.

Equation A4 shows that as filaments drag the adhesion site toward the inner part of the cell, the substrate reaction  $F_{ex}(t)$  increases linearly with time: the higher the substrate stiffness, the more rapid the increase in reaction force. At the instant of dissociation, the most likely force exerted on the adhesion site  $\langle F(k) \rangle$ , exhibits a classical logarithmic dependence on loading rate (8) modulated by the contribution of the activation energy characterizing the adhesion site considered:

$$\frac{\langle F(k) \rangle}{f_\beta} \approx \ln \left\{ \frac{k}{J f_\beta / V_R} \right\} + \frac{1}{f_\beta} \frac{\langle \Delta U \rangle}{\rho_f}. \quad (\text{A5})$$

with  $f_\beta = k_B T / \rho_f$ , the single molecule force level for bond dissociation used as a force scale ( $\sim 13$  pN (9)),  $k_B T$  is the thermal energy scale ( $\sim 4$  pN  $\times$  nm at biological temperature),  $\rho_f$  ( $\sim 0.3$  nm) is the distance at which  $U(\rho, S)$  reaches its maximum, i.e., the site dissociates.  $k_0 (= J f_\beta / V_R)$  represents a stiffness scale that characterizes the dynamic properties of the adhesion site at the molecular level:  $J [= J_0 \exp(-\frac{\Delta U}{k_B T})]$  the attempt rate for escape out of the well or rate of dissociation that depends on 1), local curvature of  $U(\rho)$  in the vicinity of dissociation; 2), friction coefficients; and 3), temperature. For an activation energy of the order of 20  $k_B T$  corresponding to weak protein-protein links such as a single link activation energy integrin-VCAM, the rate of dissociation  $J_0$  starts at  $\sim 10^9$ – $10^{10}$  Hz and ends at 1 Hz that makes difficult precise quantification of  $J$  without additional specific experiments that are beyond the scope of this study. In Eq. A5,  $\langle \Delta U \rangle$ , is the likelihood value of activation energy of the potential during dissociation, or thermal average of the passive ( $S = -1$ ) and active ( $S = 1$ ) activations energies, i.e.,

$$\langle \Delta U \rangle = \Delta U + 1/2 \Delta \Delta U (1 + \langle S \rangle_F) \quad (\text{A6})$$

with  $\Delta U$  and  $\Delta \Delta U$  the activation energy for escape out of the potential well (i.e., dissociated adhesion site) at  $S = -1$  and active  $S = 1$  respectively. The logarithmic dependence on substrate rigidity is expected to occur up to a force level  $F_c$  corresponding to the threshold rigidity where the energies of the active and passive states degenerate ( $F_c = \Delta G / d^*$ ) and the dissociation force level diverges (Fig. 7). For soft substrates, the force loading rate ( $k V_R$ ) is low and the site will dissociate from the filaments at a low reaction force level because  $\langle F(k) \rangle$ , is low (see Eq. A5), potentially initiating a succession of binding-dissociation-rebinding cycle for this site. For stiffer substrates, the elastic reaction force is higher and the dissociation force reaches a higher level (see Eq. A3). Using normalized quantities defined from the force ( $f_\beta$ ),

energy ( $k_B T$ ), and the distance ( $\rho_f$ ) scales indicated above, Eq. A1, A5, and A6 are combined to provide the self-consistency condition for  $\langle F(k) \rangle$ :

$$\tilde{F}(\tilde{k}) \approx \ln \tilde{k} + \left[ \Delta \tilde{U} + \frac{\Delta \Delta \tilde{U}}{2} \left\{ 1 + \tanh \left[ \left( \tilde{F}(\tilde{k}) - \tilde{F}_c \right) \frac{d^*}{\rho_f} \right] \right\} \right]. \quad (\text{A7})$$

Fig. 7 summarizes the results obtained for a given dynamic adhesion site (see Results for explanation).

Note that AECs correspond to adhesion sites with the highest maturation (or affinity, i.e.,  $S$ -values being in the range  $[0 \rightarrow 1]$ ) that means highest dissociation forces. Energy values of such a reinforced link could easily approach 100  $k_B T$ , and might correspond to dissociation forces in the range 50–100 pN. Single-bond mechanics of macrophage adhesion via a variety of specific ligands has been done by Knöner et al. (15), leading to a maximum dissociation force of 50 pN at loading rates of 450 pN/s, i.e., 10 pN at 10 pN/s loading rate (see Fig. 11 in Knöner et al. (15)), which confirms that AMs adhesion sites have rupture forces markedly smaller than AECs (Fig. 7).

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